STATE UNIVERSITY OF NEW YORK COLLEGE OF TECHNOLOGY CANTON, NEW YORK



MASTER SYLLABUS

COURSE NUMBER – COURSE NAME MKTX 370 – Mechatronics Laboratory II

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Canino School of Engineering Technology

Department: Mechatronics Engineering Technology

Semester/Year: Fall/2018

A. <u>TITLE</u>: Mechatronics Laboratory II

B. <u>COURSE NUMBER</u>: MKTX 370

C. <u>CREDIT HOURS</u>: (Hours of Lecture, Laboratory, Recitation, Tutorial, Activity)

Credit Hours: 1
Lecture Hours: per week
Lab Hours: 3 per week
Other: per week

Course Length: 15 Weeks

D. <u>WRITING INTENSIVE COURSE</u>: Yes \square No \boxtimes

E. <u>GER CATEGORY</u>: None: Yes: GER *If course satisfies more than one*: GER

F. <u>SEMESTER(S) OFFERED</u>: Fall Spring Fall & Spring

G. <u>COURSE DESCRIPTION</u>:

This mechatronics laboratory emphasizes the applications of analog electronics, digital electronics, sensors and transducers, actuators, and microcontrollers. Laboratory experiments are designed to give the student hands-on experience with components and measurement equipment used in the design of mechatronic products. Design and construction of mechatronics systems are emphasized

H. <u>PRE-REQUISITES</u>: None Yes X If yes, list below:

MKTX 320

<u>CO-REQUISITES</u>: None Yes If yes, list below:

MKTX 325

I. <u>STUDENT LEARNING OUTCOMES</u>: (see key below)

By the end of this course, the student will be able to:

<u>Course Student Learning Outcome</u> [SLO]	<u>Program Student Learning</u> <u>Outcome</u> [PSLO]	<u>GER</u> [If Applicable]	<u>ISLO & SUBSETS</u>	
Distinguish the basic elements underlying analog and digital electronics	a, b, k		2-Crit Think ISLO ISLO	CA IA Subsets Subsets
Use sensors, actuators, microcontrollers, and embedded software in mechatronics applications	a, b, c, k		2-Crit Think 3-Found Skills ISLO	CA IA IM Subsets
Design and devlop system models for mechatronic systems.	a, b, c, k		2-Crit Think ISLO ISLO	CA IA Subsets Subsets
Design and develop control architectures for mechatronic systems	a, b, c, k		2-Crit Think ISLO ISLO	CA IA Subsets Subsets
Tune, modify, and implement control systems in mechatronics projects	a, b, c, k		2-Crit Think ISLO ISLO	CA IA Subsets Subsets
Demonstrate effective team-work and collaborative skills	d		4-Soc Respons ISLO ISLO	T Subsets Subsets Subsets
Demonstrate comfortability with giving oral and written presentaitons	g1		1-Comm Skills ISLO ISLO	O Subsets Subsets Subsets

KEY	Institutional Student Learning Outcomes [ISLO 1 – 5]
ISLO	ISLO & Subsets
#	
1	Communication Skills
	Oral [O], Written [W]
2	Critical Thinking
	Critical Analysis [CA], Inquiry & Analysis [IA], Problem
	Solving [PS]
3	Foundational Skills
	Information Management [IM], Quantitative Lit,/Reasoning
	[QTR]
4	Social Responsibility
	Ethical Reasoning [ER], Global Learning [GL],
	Intercultural Knowledge [IK], Teamwork [T]
5	Industry, Professional, Discipline Specific Knowledge and
	Skills

J. <u>APPLIED LEARNING COMPONENT:</u>

Yes	\square	No	
100	νv	110	

If YES, select one or more of the following categories:

Classroom/Lab
 Internship
 Clinical Placement
 Practicum
 Service Learning
 Community Service
 Classroom/Lab
 Civic Engagement
 Creative Works/Senior Project
 Research
 Entrepreneurship
 (program, class, project)

K. <u>TEXTS</u>:

Faculty-Created Lab Manual

L. <u>REFERENCES</u>:

The Next Step in Training in Mechatronics Technologies, Lab-Volt Systems Inc., Farmingdale, NJ

M. <u>EQUIPMENT</u>: None Needed: Computers with MatLab, Simulink, and Data Acquisition capabilities

N. **<u>GRADING METHOD</u>**: A-F

0. <u>SUGGESTED MEASUREMENT CRITERIA/METHODS</u>:

- Lab practical
- Lab-reports
- Projects
- Participation & Team Work

P. <u>DETAILED COURSE OUTLINE</u>:

See laboratory outline.

Q. <u>LABORATORY OUTLINE</u>: None Yes X

I. Fluid Power Circuit

II. Electro-Pneumatic System

III. Speed control in AC and DC drives

IV. Servo controller interfacing with DC motors

V. Proportional Integral Derivative (PID) controller design and development.

VI. Stepper motor microcontroller system

VII. Modeling and digital simulation of electrical, hydraulic, and pneumatic systems using MatLab and Simulink

VIII. Data logging, archiving, and mining

IX. Independent Component Analysis

X. Principle Component Analysis

- XI. Fundamentals of Machine Learning I XII. Fundamental of Machine Learning II
- XIII. Implementing Machine Learning and Decision

Systems