

# SPECIAL THANKS

Toby Lancto for donating the snowblower!

# RC Snow Blower

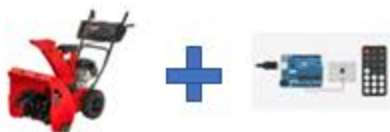
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Dr. Lucas Craig — Mech 477 Capstone Project



## Introduction

This Capstone Project aims to take an existing snowblower and provide remote-control motion (forward and reverse). This will involve...



## Design Criteria

### Engaging System

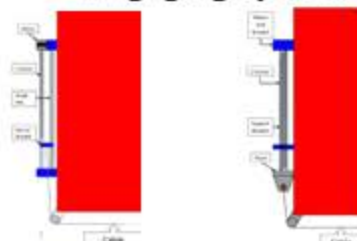
- Low cost: ~\$100
- Simplicity
- High Effectiveness—0.17

### Motion System

- Low cost: ~\$120
- High Effectiveness—0.15
- Long-term sustainability
- Programmable to increase or decrease gears

## Preliminary Designs

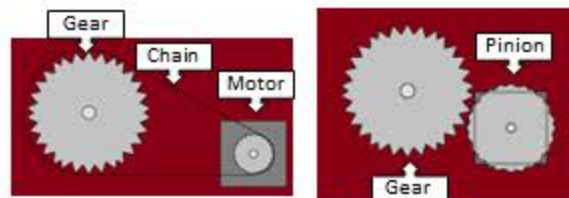
### Engaging System



### Weighted Objectives Table

Drive control		#1		#2	
Comparison Criteria	Weight	Score	Weight	Score	Weight
Cost	8	2	16	2	16
Difficulty	5	3	15	2	10
Sustainability	10	2	20	4	40
Effectiveness	10	5	50	5	50
<b>Total:</b>	<b>33</b>	<b>Total:</b>	<b>101</b>	<b>Total:</b>	<b>116</b>

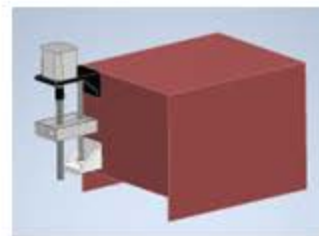
### Motion System



### Weighted Objectives Table

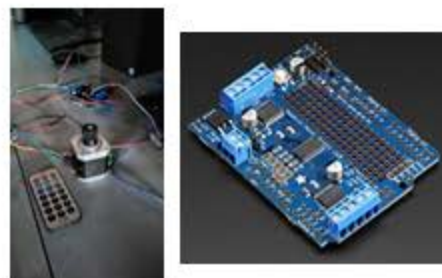
Motion System		#1		#2	
Comparison Criteria	Weight	Score	Weight	Score	Weight
Cost	8	2	16	3	24
Difficulty	5	3	15	1	5
Sustainability	10	5	50	3	30
Effectiveness	10	5	50	4	40
<b>Total:</b>	<b>33</b>	<b>Total:</b>	<b>131</b>	<b>Total:</b>	<b>99</b>

## Final Designs / Results



<More models to come>

## Experimental Testing



<More photos to come>

## Capstone Objectives

- Design an electro-mechanical system for engaging the motion
- Design an electro-mechanical system to forward and reverse
- Create a remote-control system using Arduino for forward and reverse motion
- Create a design report and poster presentation.

## Research



MAX Remote controlled Snow Blower (MAX, 2021)



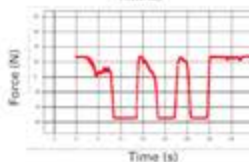
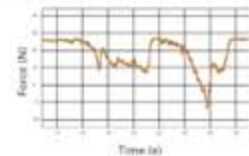
Snowbot (Snowbot, 2021)

Both existing models are not remote-controlled, but they are fully autonomous. Some future work for our project would be to make our blower independent like these.

## Background



## Initial Testing



## Contributions

Area	Start	Finish
Core Arduino	Developed two concepts for testing systems, #1 & #2	Created concepts for testing system
	Design Report	Created code for motor
	Created .PDF file including formatting, adding information and graphs, #1 & #2	Helped with PCB
	Worked with professor, coding and design for engage/disengage system	Created and worked on engage/disengage system
Motion	Worked with professor, coding and design for forward/reverse system	Designed forward/reverse system
	Motor	Created and worked on motor
	System for individual activities, various models	Designed and worked on system

## Complications

- Initial design for the engage system failed
- Time constraints with a two-man team was limited